

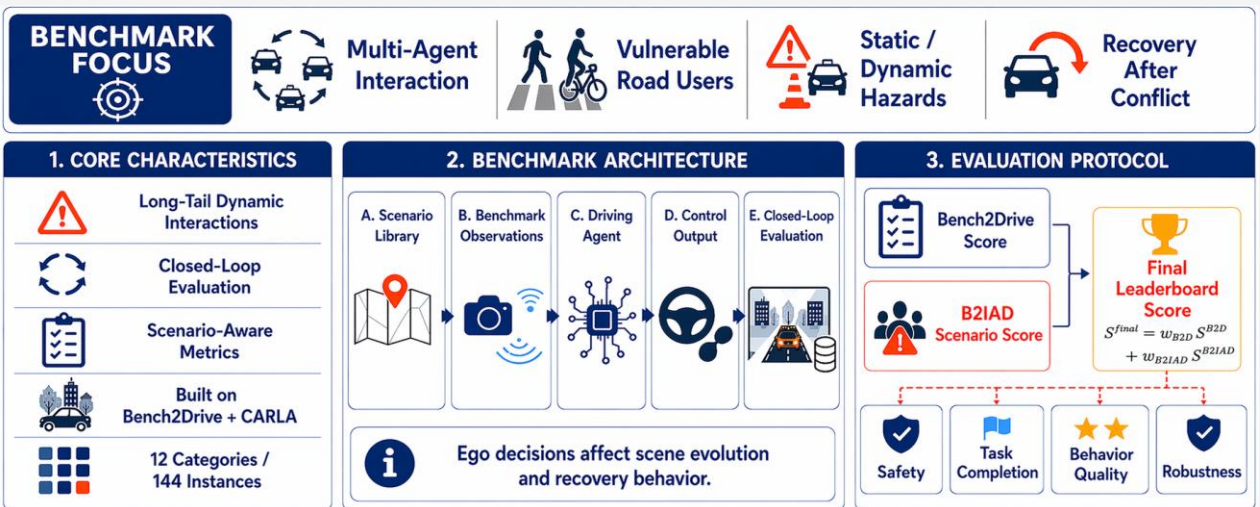


10th CAA International Conference  
 Vehicular Control and Intelligence (CVCI 2026)  
 Oct. 23th to 25th, 2026, Shanghai, China

# CVCI 2026 BenchMark: Bench2InterActDrive End-to-End Autonomous Driving Evaluation

Driven by the rapid progress of end-to-end autonomous driving, there is a growing need for benchmarks that can systematically evaluate model safety, robustness, and generalization in safety-critical and long-tail traffic scenarios. The 2026 Benchmark Challenge—Bench2InterActDrive for End-to-End Autonomous Driving Evaluation, organized as a challenge session of CVCI 2026, is proposed to address this need through a closed-loop and behavior-oriented evaluation framework. Built upon the Bench2Drive framework and utilizing the CARLA simulator, the benchmark features 12 categories and 144 scenario instances inspired by real-world intelligent driving test cases, covering extreme interactions, multi-agent traffic, and atypical traffic behaviors. To ensure a fair and informative assessment, the challenge adopts a hybrid scoring protocol that combines standard route-level driving performance with scenario-aware behavioral evaluation, preventing overly conservative or stop-only strategies from receiving artificially high scores. By providing a reproducible and challenging benchmark platform, this initiative aims to support students and researchers in developing more reliable end-to-end autonomous driving systems.

The [benchmark description](#) and the official [GitHub page](#) provide challenge details, benchmark access, evaluation resources, and related updates.



## Schedule

Open the problem with data: April 24th, 2026  
 Submission of paper and challenging results: July 1st, 2026  
 Final results submission: September 1st, 2026

## Contact

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